

27/8875

10/530138

EL899322703US

April 4, 2004

JC13 Rec'd PCT/PTO 04 APR 2005

1 COLOR NAMING, COLOR CATEGORIZATION AND DESCRIBING COLOR

2 COMPOSITION OF IMAGES

3 **TECHNICAL FIELD:**

4 The present invention is directed to digital images. It is more particularly directed to
5 color management and color analysis methodologies. It is more specifically directed to
6 color categorization, color naming, and color composition of images, video and
7 multimedia objects.

8 **BACKGROUND:**

9 Color is one of the main visual cues and has been studied extensively on many different
10 levels, starting from the physics and psychophysics of color, to the use of color principles
11 in practical problems. These include accurate rendering, display and reproduction, image
12 filtering, coding, retrieval, and numerous other applications in scientific visualization,
13 computer graphics, image and video processing. Interestingly, although color naming
14 represents one of the most common visual tasks, it has not received significant attention
15 in the engineering community. Yet today, with rapidly emerging visual technologies and
16 multimedia, and the development of sophisticated user interfaces and human-machine
17 interactions, the ability to name individual colors, point to objects of a certain color, and
18 convey the impression of color composition becomes an increasingly important task.
19 Color cues can be used in interactive visualization and computer graphics. Color naming
20 facilitates natural user interface design. The extraction of higher-level color descriptors
21 represents a challenging problem in image analysis and computer vision, as these
22 descriptors often provide link to image content. When combined with image
23 segmentation, it would be advantageous to be able to use color naming to select objects
24 by color, describe the appearance of the image and even generate semantic annotations.

1 For example, regions labeled as light blue and strong green may represent sky and grass,
2 vivid colors are typically found in man-made objects, while modifiers such as brownish,
3 grayish and dark convey the impression of the atmosphere in the scene.

4 The applications mentioned so far use a flexible computational model for color
5 categorization, color naming or extraction of color *composition* (i.e. color appearance of a
6 given scene or image to a human observer). Modeling human behavior in color
7 categorization involves solving, or at least providing some answers to several important
8 problems. The first problem involves the definition of the basic color categories and
9 “most representative examples”, called prototypical colors, which play a special role in
10 structuring these color categories. Another issue is how to expand the notion of basic
11 color terms into a “general” yet precise vocabulary of color names that can be used in
12 different applications. The next problem involves the definition of category membership.
13 Although the idea that color categories are formed around prototypical examples has
14 received striking support in many studies, the mechanisms of color categorization and
15 category membership are not yet fully understood.

16 According to the theories postulated to explain human perception, color vision is initiated
17 in retina where the three types of cones receive the light stimulus. The cone responses are
18 then coded into one achromatic and two antagonistic chromatic signals. These signals are
19 interpreted in the cortex, in the context of other visual information received at the same
20 time and the previously accumulated visual experience (memory). Once the intrinsic
21 character of colored surface has been represented internally, one may think that the color
22 processing is complete. However, an ever-present fact about human cognition is that
23 people go beyond the purely perceptual experience to classify things as members of
24 categories and attach linguistic labels to them. Color is no exception. That color
25 categories are perceptually significant can be demonstrated by the “striped” appearance of
26 the rainbow. In physical terms, the rainbow is just a light with the wavelength changing
27 smoothly from 400-700 nm. The unmistakable stripes of color in the rainbow suggest an
28 experimental basis for the articulation of color into at least some categories. However, to

1 model color naming, it is not sufficient to define the color names as functions of the
2 wavelength range. This would account only for pure monochromatic stimuli, which are
3 very rare in real-world situations, and would also leave out non-spectral colors like
4 brown, white and black. Breakthroughs in the current understanding of color
5 categorization came from several sources. This includes a cross-cultural study, which
6 studied the color naming behavior with subjects from variety of languages. Twenty
7 languages were examined experimentally and another 78 through the literature review
8 and discovered remarkable regularities in the shape of the basic color vocabulary. As a
9 result of their study, a concept of basic color terms were introduced which lead to work
10 on defining the color categories corresponding to these basic terms. Eleven basic terms
11 were identified in English: black, white, red, green, yellow, blue, brown, pink, orange,
12 purple and gray. Experiments also demonstrated that the humans perform much better in
13 picking the “best example” for each of the color terms than in establishing the boundaries
14 between the categories. This lead to the definition of focal colors representing the centers
15 of color categories, and the hypothesis of graded (fuzzy) membership. Many later studies
16 have proven this hypothesis, indicating that prototypical colors play a crucial role in
17 internal representation of color categories, and the membership in color categories seem
18 to be represented relative to the prototype. Unfortunately, the mechanism of color naming
19 is still not completely understood. There exist few theoretical models of color naming
20 based explicitly on neurophysiology of color vision and addressing the universality of
21 color foci and graded membership. Apart from not being developed or implemented as
22 full-fledged computational models, these have important drawbacks. In one model
23 membership in color categories is formalized in terms of fuzzy set theory, by allowing the
24 objects to be members of a given set to some degree. In terms of color categories, this
25 means that a focal or prototypical color will be represented as having a membership
26 degree of 1 for it’s category. Other, non-focal colors will have membership degrees that
27 decrease systematically with the distance from the focal color in some color space.
28 However, this model considers only four fuzzy sets (red, green, yellow and blue), and
29 supporting other color terms requires the introduction of new and ad hoc fuzzy set
30 operations. Furthermore, it is not clear how the non-spectral basic color categories, such

1 as brown, pink and gray are to be dealt with, nor how to incorporate the learning of color
2 names into the model. Another model defines four physical parameters of the stimulus:
3 wavelength, intensity, purity and adaptation state of the retina. According to this model,
4 the pre-cortical visual system performs analog-to-digital conversion of these four
5 parameters, and represents eleven basic color categories as specific combinations of the
6 quantized values. Although interesting for its attempt to take adaptation into account, this
7 model is clearly a gross simplification, which cannot hold in general.

8 Although color spaces allow for color specification in unambiguous manner, in everyday
9 life colors are mainly identified by their names. Although this requires a fairly general
10 color vocabulary and is far from being precise, identifying a color by its name is a method
11 of communication that everyone understands. Hence, there were several attempts towards
12 designing a vocabulary, syntax and standard method for choosing color names. The
13 Munsell color order system known to those skilled in the art, is widely used in
14 applications requiring precise specification of colors. Examples include production of
15 paints, textiles, etc. It is often used as an industry standard, complemented by Munsell's
16 Book of Color which includes 1,200 precisely controlled samples of colors (chips). The
17 chips are arranged such that unit steps between them are intended to be perceptually
18 equal. Each chip is identified by a 3-part code. The brightness scale is represented by the
19 Munsell value with black denoted by 0/ and white by 10/. Munsell chroma increases in
20 steps of two ($/2$, $/4$, \dots , $/10$). The hue scale is divided into 10 hues: red (R), yellow-red
21 (YR), yellow (Y), green-yellow (GY), green (G), blue-green (BG), blue (B), purple-blue
22 (PB), purple (P), red-purple (RP), each hue can be further divided into ten sections. One
23 notable disadvantage of the Munsell system for the color-based processing is the lack of
24 the exact transform from any color spaces to Munsell. For example, a transform proposed
25 by others is fairly complicated and sometimes inaccurate for certain regions of CIE XYZ.

26 The first listing of over 3000 English words and phrases used to name colors was devised
27 by Maerz and Paul and published in a Dictionary of colors. Even more detailed was a
28 dictionary published by The National Bureau of Standards. It included about 7500

1 different names that came to general use in specific fields such as biology, geology,
2 philately, textile, dyes and paint industry. Both dictionaries include examples of rare or
3 esoteric words, and the terms are listed in entirely unsystematic manner, making them
4 unsuitable for general use. Following the recommendation of the Inter-Society Council,
5 the National Bureau of Standards developed the ISCC-NBS dictionary of color names for
6 267 regions in color space. This dictionary employs English terms to describe colors
7 along the three dimensions of the color space: hue, brightness and saturation. One
8 problem with the ISCC-NBS model is the lack of systematic syntax. This was addressed
9 during the design of a new Color-Naming System (CNS). The CNS was based in part on
10 the ISCC-NBS model. It uses the same three dimensions, however the rules used to
11 combine words from these dimensions are defined in a formal syntax. An extension of the
12 CNS model, called the Color-Naming Method (CNM), uses a systematic syntax similar
13 to the one described in the CNS model, and maps the color names from the CNM into
14 color ranges in the Munsell system. All the aforementioned methods are closely related to
15 the Munsell model and thus provide explanation on how to locate each name within the
16 Munsell color space. However, it is not obvious how to use these methods to
17 automatically attach a color name to a color sample, point out examples of named colors,
18 describe the color region and objects in a scene, and ultimately communicate the color
19 composition of the image.

20 One approach to these problems discloses a process for creating a color name dictionary
21 and for querying an image by color name. The steps of the disclosed process are to
22 identify a preferred color space, which is then divided into a plurality of color space
23 segments, and a color name is assigned to each of the plurality of color segments. In
24 accordance with this invention, a color name dictionary defines a set of the color names
25 and color name boundaries, advantageously in a three-dimensional visually uniform color
26 space. Each color name is represented by a volume in the color space. Given an input
27 pixel, the color name is assigned using a disclosed method, which identifies the volume
28 that includes the color value of the input pixel. However, many psychophysical
29 experiments, , have demonstrated that the humans perform much better in picking the

1 “best example” for each of the color terms than in establishing the boundaries between
2 the color names or color categories, and most importantly, that prototypical colors play a
3 crucial role in internal representation of color categories, as the membership in color
4 categories seem to be represented relative to the prototype.

5 The aforementioned approach also provides a method for querying image by color name.
6 The steps of the disclosed process involve direct application of the color naming method
7 to individual image pixels and computing the fractional count for each color name from
8 the dictionary. To allow for more specific descriptions, the image is divided into a fixed
9 set of regions defined by the image region dictionary (center, bottom, bottom left, etc.),
10 the fractional counts are also computed for each region, and that representation is used to
11 answer queries such as “Which of images in the database have most of color name red in
12 top-right region”. However, this representation is not in agreement with the way humans
13 perceive images and describe their color composition. Humans do not perceive image
14 content as being in top or bottom right portion of the image -- they perform logical
15 analysis (image segmentation) and extract meaningful regions and objects from that
16 image. Humans then describe these objects with a single color, e.g. “sky is blue”, not by
17 the fractional count of the color names occurring within. Furthermore, it is well known
18 that although digital images may include millions of colors, only a very small number of
19 these are actually perceived. Therefore, the direct representation of the color name
20 histogram does not match the representation generated by the human visual system.

21 A computational model that is better matched to human behavior in naming individual
22 colors has been proposed in this method uses color naming data and applies a variant of
23 the Gaussian normal distribution as a category model. However, this method is
24 constrained to the lowest level of color naming, as it was fitted to the eleven basic color
25 names. For example, although it allows for the intermediate hues, such as greenish
26 yellow, the model does not account for commonly used saturation or luminance
27 modifiers, such as vivid orange or light blue. Since the quality of color categorization
28 depends on the intricate fitting procedure, there is no straightforward extension of the

1 model to include these attributes and the model cannot be used with other sets of color
2 names.

3 As may be appreciated, due to the shortcomings of the existing methodologies, there is a
4 long-felt and unfulfilled need for a broader computational color naming method that will
5 provide more detailed color descriptions and allow for the higher-level color
6 communication to: automatically attach a color name to a color sample, point out
7 examples of named colors, describe the color region and objects in a scene, and
8 ultimately communicate the overall color composition of an image.

9 **SUMMARY OF THE INVENTION:**

10 The foregoing problems are overcome, and other advantages are realized, in accordance
11 with the presently described embodiments and their teachings. Thus, an aspect of this
12 invention is to provide methods, apparatus and systems for automatic color naming,
13 color categorization, and for the automatic derivation of color composition in images.
14 These apply to individual color values to automatically determine a color name for a
15 given color value. The method also applies to digitally represented images, to: 1)
16 automatically attach a color name to each pixel in the image, 2) automatically attach a
17 color name to the regions and objects in the image, 3) point out examples of named colors
18 within the image, 4) generate the verbal description of color composition, 5) replace
19 objects and regions with the named color, with the different color, also specified by its
20 name.

21 Another aspect is to apply, the term color value to any representation used to specify or
22 describe colors in an unambiguous manner. Example embodiments include, but are
23 not limited to (r, g, b), (L, a, b), (x, y, z), (h, s, v) vectors, when color is specified in
24 the RGB, Lab, XYZ and HSV color spaces, respectively. The provided methods are
25 generally based on the vocabulary of color names and color naming metric derived from

1 perceptual experiments. The method follows relevant studies on human categorization,
2 and, captures human behavior in describing individual colors and color composition of
3 complex images (an image that contains multiple objects, patterns, edges, or colors).
4 There are numerous interesting applications for color naming in image processing,
5 analysis and computer vision. To start with, using color names to label regions can often
6 provide meaningful image segmentation, since the neighboring regions that share the
7 same color name are very likely to belong to the same object. When combined with image
8 segmentation, color naming can be used to select objects by color, describe the
9 appearance of the image and even generate semantic annotations, since in many cases
10 color names only, or in combination with other image features (such as spatial attributes,
11 boundary and size features), provide valuable information about images and reveal their
12 semantic meaning. For example, regions labeled as light blue and strong green may
13 represent sky and grass, vivid colors are typically found in man-made objects, while
14 modifiers such as brownish, grayish and dark convey the impression of the atmosphere in
15 the scene.

16 The techniques and apparatus described here possesses several desirable properties. First,
17 color naming operation is performed in a perceptually controlled way, so that the names
18 attached to different colors reflect perceived color differences among them. Segmenting
19 the color space into the color categories produces smooth regions. The methods account
20 for the basic color terms and uses systematic syntax to combine them. It respects the
21 graded nature of category membership, the universality of color foci, and produces results
22 in agreement with human judgments. The first step in the method for determining the
23 color name for an arbitrary input color this method, involves the selection of a balanced
24 and well-represented set of color prototypes, i.e. vocabulary, and the corresponding color
25 naming syntax. Color categorization is then carried through the color naming metric.
26 Assuming a well-represented set of color name prototypes, the metric computes the
27 distance between the input color and all the prototypes from the vocabulary. The
28 “optimal” color name for the input color value is then assigned by taking the color name
29 prototype, which corresponds to the minimum value of the color naming metric. The

1 color naming metric is designed to overcome the limitations of existing color distance
2 functions (such as Euclidean distance in a selected color space), and most importantly to
3 account for the way humans perceive differences in the color-name domain.

4 Also described is a method for attaching the color name to each meaningful region in a
5 digital image. According to this method, digital image is first subjected to the chromatic
6 transformation to compensate for the differences in illumination conditions, with respect
7 to both intensity and spectral characteristics. In the next step image pixels are subjected to
8 labeling procedure. In one, but not limiting embodiment, each pixel is labeled uniform,
9 texture, color edge, texture edge or noise. These labels drive the adaptive low-pass
10 filtering operation that accounts for the spatial averaging processes in the early stages of
11 the human visual system. The smoothed image is then subjected to color segmentation.
12 This operation produces a *simplified* version of the image, i.e. a version which resembles
13 the way humans interpret color information. The mean color value for each region from
14 the color segmentation is then mapped into the corresponding color name, using the
15 previously described method. The technique described also allows the user to provide an
16 example color name, and then inspects the color name attached to image regions to find
17 the occurrences of the specified color name in the input image. The method is not limited
18 to digital images or collections of digital images (such as digital photographs, digital
19 artwork, output of scanning devices, etc.), it also applies to video, multimedia, or any
20 representation that involves the spatial arrangement of color values. A simplified
21 representation of a scene is a representation that reduced only to the objects and regions
22 that are perceived/processed by a human observer.

23 Also described is a method for deriving a verbal description, a description that can
24 verbalized, for describing the color composition of a digital image. To extract color
25 composition, the method starts from the color-segmented image, and using the color
26 naming metric attaches the color name to all perceptually important pixels. In the next
27 step, the histogram of color names is computed and used to generate the description of
28 color composition. The structure and syntax of the designed vocabulary of color names,

1 allow for descriptions at different accuracy levels that simulate different color naming
2 patterns in humans. In the present, but not limited embodiment, at the fundamental level,
3 the color names are expressed as <generic hue> (such as “red” or “blue”) or <generic
4 achromatic term> (“gray”, “black”, “white”) from the syntax. At the coarse level, color
5 names are expressed as <luminance> <generic hue>, (e.g. “light blue”) or <luminance>
6 <generic achromatic term> (e.g. “dark gray”). At the medium level, color names are
7 obtained by adding the <saturation> to the coarse descriptions (e.g. “vivid light blue”).
8 Finally, at the detailed level, the <hue modifier> is added (e.g. “light vivid greenish
9 blue”).

10 **BRIEF DESCRIPTION OF THE DRAWINGS:**

11 The foregoing and other aspects of these teachings are made more evident in the
12 following detailed description of the invention, when read in conjunction with the
13 attached drawing figures, wherein:

14 Fig. 1 is a simplified block diagram of a data processing system that is suitable for
15 practicing this invention;

16 Figs. 2A-2K illustrates an example embodiment of a color naming vocabulary;

17 Fig. 2L illustrates an example of an embodiment of a color naming syntax;

18 Fig. 3 is a logic flow diagram that illustrates a method for computing a similarity metric
19 between an arbitrary color value c_x and a color name prototype c_p ;

20 Fig. 4 is a logic flow diagram that illustrates a method for attaching a color name to a
21 color sample c_x ;

1 Fig. 5 is a logic flow diagram that illustrates an example implementation of a method for
2 computing a similarity metric between a color value cx and a color name prototype cp ;

3 Fig. 6 is a diagram illustrating an example embodiment of the method for computing the
4 color name distance between an input color cx , and a prototype color from the vocabulary
5 cp (i.e. the computation of the color naming metric);

6 Fig. 7a shows an application of a color naming method to name different color regions for
7 color names assigned to the “color circle” in the HSL space defined with $s = 83$ and
8 $l = 135$;

9 Fig. 7b shows an application of a color naming method to name different color regions
10 for transition of color names along the black-red, red-yellow, purple-white, and
11 black-green lines in the RGB space;

12 Fig. 8 is a logic flow diagram that illustrates an image smoothing algorithm and detection
13 of important regions and objects in an image.

14 Fig. 9 is a logic flow diagram that illustrates an example implementation of the image
15 smoothing algorithm, followed by the detection of important regions and objects in the
16 image;

17 Fig. 10 is a logic flow diagram that illustrates a method for attaching a color name to the
18 regions and objects in the image;

19 Fig. 11 is an example result of image smoothing, region detection, and attaching the color
20 names to the important regions and objects in the image;

21 Fig. 12a is a logic flow diagram that illustrates a method for pointing out examples of
22 selected color in the image;

1 Fig. 12b is a logic flow diagram that illustrates a method for replacing a selected color
2 with a different color;

3 Fig. 13 illustrates an example embodiment of the rules that describe different accuracy
4 levels in expressing the color composition of an image;

5 Fig. 14 is a logic flow diagram that illustrates a method for the computation of the
6 description of the image color composition;

7 Fig. 15 is an example of the result of the computation of color composition; and

8 Fig. 16 is illustrates some possible applications of the color naming methods.

9 **DETAILED DESCRIPTION OF THE INVENTION**

10 This invention provides image processing methods, apparatus and systems that are
11 generally based on human perception, which: a) attaches a color name to an input color
12 sample, b) describes objects and regions in an image with their color names, and c)
13 generates the verbal description of image color composition. The methods are used in
14 many image processing, computer vision, graphics and visualization applications. The
15 methods enable development of better user interfaces and better man-machine
16 interaction. The methods are implemented using a set of image processing algorithms,
17 that analyze the input color value to determine optimal color name from the vocabulary of
18 color names, and then process the image to break it into meaningful regions, determine
19 the perceived color value of these regions and attach the color names appropriately.

20 A first example of a method automatically assigns a color name to an input color value, or
21 color sample, without requiring the use of a labor-intensive process where each color

1 sample is labeled manually with the corresponding color name. A second example
2 method, provides an algorithm to automatically label regions and objects in an image
3 with the best describing color names and then generates the verbal description of the
4 overall color composition. These are advantageous in image analysis, in applications
5 dealing with multimedia databases, as well as in the fields of artificial intelligence,
6 visualization, computer graphics, user-interface design and human-machine interaction.
7 As used herein, a scene is consistent with human observation of the scene is consistent in
8 a sense that all the important objects, regions and edges are preserved in the simplified
9 representation, as well as all the colors that the human observer perceives.

10 Figure 1 is a simplified block diagram of an example of an embodiment of a data
11 processing system, 100 that is suitable for practicing the invention, as well as the
12 teachings of the present invention. The data processing system 100 includes at least one
13 data processor 101 coupled to a bus 102 through which the data processor 101 may
14 address a memory subsystem 103, also referred to herein simply as the memory 103. The
15 memory 103 may include RAM, ROM, and fixed or removable storage devices. The
16 memory 103 is assumed to store a program with the program instructions for causing the
17 data processor 101 to execute methods in accordance with the teachings of the invention.
18 Also stored in the memory 103 is at least one database including data representing a
19 vocabulary of color names or pointers to externally stored vocabulary data. Also stored in
20 the memory 103 is a set of color values (or references to externally stored color values),
21 and/or digital image data (or references to externally stored digital image data), and the
22 resulting color naming data (i.e. data obtained by applying the teachings of the invention).
23 The color values may include any color representation used to unambiguously specify
24 color, such as three-element vector specification in the RGB, XYZ, HSV, Lab, Luv, or
25 any other system which may be used to specify colors. The color values may be entered
26 into the memory 103, through any input device (such as keyboard, microphone,
27 colorimetric device, etc.), also they may be obtained through the mean of digital camera,
28 scanner, or by use of any pointing device that selects or produces a certain color, such as
29 mouse, pen, etc. The color values may also be obtained by reading the color information

1 from digital images, by means of speech or character recognition, web pages, 3D models,
2 simulation results, etc. The digital image data represents any spatial arrangement of color
3 values. This may include photographs obtained from a digital camera, or any device that
4 outputs digital images (such as camcorder, electronic microscope, telescope, medical
5 imaging device, etc.), images obtained from a conventional film camera and scanned or
6 digitized into the memory 103, computer generated images, or artworks that are
7 photographed and scanned or digitized into the memory. In general digital image data
8 may be any desired type or types of images, including digitally stored artworks, designs,
9 paintings, forms, web page layouts, medical images, movie shots, screens and shots from
10 video games, etc.

11 In some embodiments, the data processor 101 is coupled through the bus 102 to a
12 network interface 106 that provides bidirectional access to a data communication network
13 107, such as intranet and/or internet. Coupled to the network 107 can be on or more
14 sources and/repositories of external data, such as a remote digital image database 108, or
15 remote database of color samples and/or color values 109, reachable through an
16 associated server 110. The data processor 101 is also advantageously coupled through the
17 bus 102, or the network 107, to at least one peripheral device 111, such as scanner 111A,
18 printer 111B, digital camera 111C, medical imaging device 111D, microphone 111E, etc.

19 In general these teachings may be implemented using one or more software programs
20 running on a personal computer, a server, a mainframe computer, a portable computer,
21 PDA, an embedded computer, or by any suitable type of programmable data processor.
22 The use of this invention substantially improves analysis, description, annotation and
23 other information processing tasks related to digital images and digital color data. It also
24 substantially improves human-machine interaction and user interface design. The
25 teachings of this invention can also be configured to provide real-time processing of
26 color-related and/or image-related information. The methods may be used to process the
27 color data and/or digital image data stored in or referenced by the database 104 or in a

1 remotely stored databases 108, 109 over the network 107 and in cooperation with the
2 server 110.

3 The foregoing system and methods provide for verbally (i.e. through color names)
4 describing individual colors specified by their color values, colors of object in digital
5 images, as well as for generating the description of the overall color composition, based
6 on the syntax and vocabulary of color names, and the color naming metric. The
7 vocabulary, syntax and the metric are derived advantageously from perceptual
8 experiments performed with human observers.

9 Figures 2A-2K illustrate an example embodiment of a vocabulary of color names, and
10 Figure 2b illustrates an example, but not limited embodiment of a color naming syntax.
11 Each entry in the vocabulary represents a color name prototype, specified by: 1) its color
12 name, which follows the formal syntax of the color naming language, and 2) its color
13 value in an arbitrary color space. Advantageously, the color value for each of the color
14 name prototypes should represent the centroid of a region (in a perceptually uniform color
15 space) that is described by the corresponding color name.

16 A set of experiments was conducted to: 1) understand human behavior in describing and
17 naming individual colors, 2) understand human behavior in naming colors within
18 complex scenes, (, 3) understanding human behavior describing color composition of
19 images, and 4) determine the reliable and general set of color names to be used as the
20 color name vocabulary. As used herein, the term *general set of color names* refers to a set
21 of color names that is widely and frequently used in everyday life, is understood by the
22 general public, and can most generally fully describe appearance of any object, scene,
23 etc.). Ten subjects participated in the experiments. The vocabulary of color names used in
24 an embodiment, of the invention, was developed starting from the set of color names
25 described by K. Kelly, and D. Judd. Through the set of subjective experiments, the names
26 of colors from the ISCC-NBS dictionary were changed to reflect human judgments in
27 color naming. In these experiments (called Color Naming Experiments) known to those

1 familiar with the art, the subjects were presented with the colors from the ISCC-NBS
2 color dictionary, and asked to name each one of them. The color patches were displayed
3 on the computer monitor.

4 In the first experiment, 64×64 pixel patches were arranged into 9×6 matrix and displayed
5 against light gray background. The names were assigned by typing into a text box below
6 each patch. After naming all the colors, the display was updated with the new set of
7 patches, until all 267 colors from the dictionary have been named.

8 In the second color naming experiment, only one 200×200 pixels color patch was
9 displayed on the screen. To analyze the agreement between these two color naming
10 experiment, for each experiment a list of corrected color names was made, i.e. the names
11 from the ISCC-NBS vocabulary were changed to reflect the opinion of the majority of
12 subjects. The two lists showed very good agreement between the experiments. The final
13 vocabulary is determined as the list from the first color naming experiment, since the
14 names were generated in the interaction with other colors, which is seen as a better
15 representation of real-life applications.

16 The two Color Naming Experiments were also useful for studying the patterns in human
17 color naming behavior. For example, the most noticeable difference between the two
18 color naming experiments was in the use of luminance modifiers. The same color was
19 often perceived brighter when displayed in a small patch (Experiment 1) than in a large
20 window (Experiment 2). Also, very pale and unsaturated (grayish) colors appeared more
21 chromatic when displayed in a smaller window. To better understand the human behavior
22 in color naming, two more subjective experiments were performed. In the first
23 experiment, called Color Listing Experiment, subjects were asked to write on a sheet of
24 paper names of at least twelve “most important” colors. In the second experiment, called
25 Color Composition Experiment, the subjects were presented with 40 photographic images
26 in a sequence and asked to name all the colors in the image. The images were selected to

1 include different color compositions, spatial frequencies and arrangements among the
2 colors, and provide broad content. The subjects were advised to use common color terms,
3 as much as possible, to avoid rare color names, and color names derived from objects and
4 materials. If they found a certain color difficult to name, they were advised to describe it
5 in terms of other colors.

6 In the Color Listing Experiment 11 basic colors from B. Berlin and P. Kay, "Basic Color
7 Terms: Their Universality and Evolution", Berkeley: University of California, 1969, were
8 found on the list of every subject. Nine subjects included beige, four included violet, two
9 included cyan and magenta, and one included gold and silver. Modifiers for hue,
10 saturation and luminance were not used. None of the subjects listed more than 14 color
11 names. The subjects maintained the same limited vocabulary when describing images in
12 the Color Composition Experiment, and added only beige to the basic colors. The
13 modifiers for hue, saturation and luminance were used only to distinguish between the
14 different types of the same hue in the single image (such as light blue for sky and dark
15 blue for water, or orange yellow and vivid yellow for two different objects). Otherwise,
16 the modifiers were seldom included into description. It was also observed that the
17 subjects were more prone to attaching the modifiers for luminance than the modifiers for
18 saturation.

19 Although most of the experimental images had rich color histograms, the subjects were
20 not able to perceive more than ten colors at once. Dark colors, which typically exist in
21 natural images due to shadows and edges, or bright colors due to highlights and
22 specularities, were never included in the description, and were named only when referring
23 to well-defined objects/regions. The subjects showed the highest level of precision in the
24 Color Naming Experiments. Most of them (8/10) frequently used modifiers for hue,
25 saturation or brightness. The modifiers for hue were designed either by joining two
26 generic hues with a hyphen, or by attaching the suffix -ish to the farther hue, and leaving
27 the closer hue unchanged. Typically, only two adjacent hues (such as purple and blue, or
28 green and yellow) were combined.

1 The findings from all four experiments were used to devise the vocabulary depicted in
2 Figure 2a. The terms for brightness are determined to be: blackish, very dark, dark,
3 medium, light, very light and whitish. The terms for saturation are determined to be:
4 vivid, strong, medium, moderate, grayish. The complete set of generic hues is determined
5 to be: red, green, yellow, blue, orange, pink, purple, brown, beige and olive, with the
6 addition of achromatic names black, white and gray. These findings were expressed in
7 the formal syntax, as illustrated in Figure 2b.

8 Having established the vocabulary of color names, in accordance with an aspect of these
9 teachings, the next step is to develop an algorithm for attaching the color name to an
10 arbitrary input color. To address the graded nature of category membership and take into
11 account the universality of color foci, the color categorization should be performed
12 through the color naming metric. Assuming a well-represented set of prototypes (foci),
13 the metric computes the distance between the input color and all the prototypes, thus
14 quantifying the difference between the input color and each color name prototype.

15 By way of introduction, Figure 3 shows a logic flow diagram that illustrates an example
16 of a method for computing a similarity metric between a color value (color sample) cx
17 and a color name prototype cp. The method is assumed to be executed by the data
18 processor 101 under control of a program or program stored in the memory 103. This
19 implementation is based on the finding that the colors that share the same distance (in
20 arbitrary color space) to a color prototype cp, may not be perceived as equally similar to
21 that prototype, in which case the color distance has to be updated proportionally to the
22 amount of dissimilarity. The computation of the color metric between an arbitrary input
23 color cx and the prototype cp, is then based on: a) computing the distance between cx and
24 cp (step 301), b) finding the optimal color match to cp for the given distance (step 302),
25 c) estimating the perceptual difference between cx and the optimal color match (step
26 303), and d) using this estimate to modify the distance between cx and cp (step 304).

1 Figure 4 is a logic flow diagram that illustrates an example of a method for attaching a
2 color name to the input color cx. Step 401 loads a vocabulary of color names, i.e. a set of
3 color prototypes. Step 402 gets the input color value cx. At step 403, the data processing
4 system compares the color value cx to the color value of each color name prototype from
5 the vocabulary of color names 405, via the color naming metric. At step 404, the data
6 processing system determines the minimum of the color naming metric and attaches the
7 corresponding color name to the input color value cx. It should be understood that the
8 present invention enables multiple vocabularies of color names 405 to be defined, such
9 as, with a different vocabulary 405 specific for a different task or application.

10 By way of introduction, Figure 5 is a logic flow diagram that illustrates an
11 implementation of an example of a method for computing a similarity metric between a
12 color value (color sample) cx and a color name prototype cp. The method is generally
13 executed by the data processor 101 under control of a program or program stored in the
14 memory 103. At step 501 the input color values are transformed into Lab and HLS
15 coordinates. At step 502 the data processing system computes the optimal perceptual
16 match to the prototype cp, for the given Lab distance. At step 505, the data processing
17 system estimates the difference between the optimal perceptual match and the input color
18 cx, and at step 506, the data processing system uses that estimate to modify the Lab
19 distance between cx and cp.

20 An advantageous embodiment is based on the experimental finding that, although
21 commonly used as measure of color similarity, Euclidean distance in the CIE Lab color
22 space has several serious drawbacks for the use as a color naming metric. A first problem
23 is related to the sparse sampling of the color space. Since the uniformity of the Lab
24 suffers from defects its “nice” perceptual properties remain in effect only within a radius
25 of few just-noticeable differences. Since the vocabulary of color names typically has a
26 small number of color names, the distances between the colors may be large and the
27 Euclidean metric only partially reflects the degree of color similarity. The other, more
28 serious problem is related to human perception of color names and their similarity.

1 Assuming an arbitrary color represented by a point cp in the Lab space, and a set of
2 neighboring colors cni , $i = 1, \dots, N$ on a circle with the radius L in that space, although all
3 the pairs (cp, cni) are equally distant, humans do not perceive them as equally similar.

4 To test the relationship between perceptual similarity, and color distances in different
5 color spaces, a subjective experiment was conducted. Four subjects participated in the
6 experiment. The subjects were given ten sets of color samples. Each set consisted of a
7 “prototype” color cp and five colors, cni , $i = 1, \dots, 5$ so that $D_{Lab}(cp, cni) = \text{const}$. The
8 distances between the prototype and the rest of the colors ranged from 6 to 30. For each
9 set the subjects were asked to order the samples according to the perceived similarity to
10 the set prototype. These sets were displayed in sequence on a computer monitor with light
11 gray background under the daylight illumination. Each color sample was displayed in the
12 100×100 pixels window and could be moved on the screen to allow for the comparison
13 with the prototype cp .

14 For all the pairs, the color distances, and angles between the color vectors were computed
15 in both Lab and HSL spaces. These measurements were analyzed and also correlated with
16 the subject’s rankings. The first thing that was observed is that for $D_{Lab} < 7$ all the colors
17 were perceived as equally similar to the prototype. In most of the other cases subjects
18 identified the best and worst match unanimously, frequently leaving other samples
19 unranked. Typically, the colors subjects failed to rank were close in all three values. For
20 the colors that were ranked by the subjects, the correlation between the subjects’ rankings
21 and rankings determined based on angle in the HSL space was 0.96. The correlation
22 between the subjects’ rankings and rankings determined based on the distance in the HSL
23 space was 0.85, and the correlation with the rankings determined based on the angle in
24 the Lab space was only 0.70. The slope of the least square regression line for the subjects’
25 rankings and the rankings assigned according to the angle in the HSL space was 0.97. The
26 slope of the least square regression line for the subjects’ rankings and the rankings
27 assigned according to the distance in the HSL space was 0.84, and the slope of the least

1 square regression line for the subjects' rankings and the rankings assigned according to
 2 the angle in the Lab space was 0.87. These results indicate that the color angle in the HSL
 3 space and the color distance in the HSL space (alone or combined) may be used as
 4 predictors of perceptual similarity between the equidistant colors, although none of these
 5 two values alone represents an accurate color naming metric.

6 The color naming metric is then designed to embody the findings from the experiment. It
 7 models the behavior of subjects in color categorization. Assuming a prototype c_p and
 8 arbitrary input color c_x , as discussed previously, for a given $D_{Lab}(c_p, c_x)$, the combination
 9 between $\theta_{HSL}(c_p, c_x)$ and $D_{HSL}(c_p, c_x)$ reflects the "reliability" or "goodness" of the Lab
 10 distance as the measure of similarity in the color name domain. Thus, this relationship is
 11 used to modify D_{Lab} in the following manner. First, the distances between c_p and c_x in
 12 the Lab and HSL color spaces is computed as:

$$13 \quad D_{Lab}(c_p, c_x) = L = \sqrt{(l_p - l_x)^2 + (a_p - a_x)^2 + (b_p - b_x)^2},$$

$$14 \quad D_{HLS}(c_p, c_x) = R = \sqrt{s_p^2 + s_x^2 - 2s_p s_x \cos(h_p - h_x) + (l_p - l_x)^2}.$$

15 In the next step, given the radius R, the data processing system finds the color

$$16 \quad c_o : (h_o, s_o, l_o), \text{ so that: } D_{HLS}(c_p, c_o) = R, \text{ and } \theta_{HSL}(c_p, c_o) = \frac{s_p s_o + l_p l_o}{\sqrt{(s_p^2 + l_p^2)(s_o^2 + l_o^2)}} = 0.$$

17 Solving (1) results in: $h_o = h_p$, $s_{o1,2} = s_p(1 \pm R / \sqrt{(s_p^2 + l_p^2)})$, $l_{o1,2} = l_p(1 \pm R / \sqrt{(s_p^2 + l_p^2)})$, and
 18 the final solution is obtained by taking a point that is satisfied.

1 This procedure is illustrated in Figure 6. According to the experimental results, given the
2 distance L , the optimal perceptual match corresponds to the direction $\theta_{HSL}(c_p, c_o) = 0$.
3 Assuming a small increment ΔR , the initial solution c_o is then updated in the following
4 manner: $R_o = D_{HSL}(c_p, c_o)$, $s_o = s_o(1 \pm \Delta R / R_o)$, and $l_o = l_o(1 \pm \Delta R / R_o)$, until $D_{Lab}(c_p, c_o) \approx D$.
5 At this point, c_o represents an optimal perceptual match to c_p , for the given Lab distance.
6 This solution is therefore denoted c_{opt} . An estimate of perceptual dissimilarity between
7 c_x and c_{opt} is then computed as a relative difference in the HSL space between c_{opt} , and
8 the projection $c_x \perp c_{opt}$:

$$9 \quad \Delta d(c_p, c_x) = \frac{d(c_p, c_{opt}) - d(c_p, c_{ox})}{d(c_p, c_{opt})} = \frac{R_o - R \cos \alpha}{R_o} = 1 - \frac{s_p s_x \cos(h_p - h_x) + l_p l_x - s_p^2 - l_p^2}{R_o \sqrt{s_p^2 + l_p^2}}$$

10 As used by the model in predicting the amount of perceptual similarity, this formula takes
11 into account both the distance and the angle in the HSL space. Therefore, this value is
12 used to modify the Lab distance between the colors c_p and c_x in the following manner:

$$13 \quad D(c_p, c_x) = D_{Lab}(c_p, c_x) + k(D_{Lab}(c_p, c_x)) D_{Lab}(c_p, c_x) \Delta d(c_p, c_x)$$

14 i.e. the Lab distance is increased proportionally to the amount of dissimilarity Δd . The
15 factor $k(L)$ is introduced to avoid modifying distances between very close points, so that
16 $k(L) = 0$ if $L < 7$, and to limit the amount of increase for large L , i.e. $k(L) = \text{const}$, if
17 $L > 30$. Figs. 7a and 7b show applications of a metric used to name different color regions
18 in the RGB and HSV color spaces. Figure 7a shows the color names assigned to the
19 “color circle” in the HSL space defined with $s = 83$ and $l = 135$. Figure 7b shows the
20 transition of color names along the black-red ($0 < r < 255$, $g = 20$, $b = 20$), red-yellow

1 (r = 235, 0 < g < 255, b = 20), purple-white (0 < r < 255, g = 0, 0 < b < 255), and
2 black-green lines (r = 20, 0 < g < 255, b = 20) in the RGB space.

3 This approach is now expanded and applied to automatically attach color names to
4 regions and objects in digital images, and to derive a verbal description of the color
5 composition in images. This embodiment, is based at least in part on the fact that the
6 human observation of a scene is typically very different from the recorded image. When
7 describing the color composition of a complex *scene* (a scene that includes multiple
8 objects, patterns, edges, or colors) human perception aims at constructing a visual
9 representation with “vivid colors” and details across a wide range of lighting conditions.
10 As a matter a fact, the very notion of a “color name” has its roots in the fact that humans
11 perceive and interpret color information independently of the light source -- the
12 phenomenon known as color constancy. On the other hand, the teachings of this invention
13 presented so far, generally only allow for naming isolated samples of colors, or attaching
14 color names to individual image pixels; the teachings do not account for color constancy,
15 or the spatial relationships and interactions among the colors.

16 An embodiment of a method that takes into account the issues listed above and aims to
17 provide a description of the scene consistent with human observation is now described.
18 The algorithm has two parts. The first part deals with the problem of color constancy,
19 while the second one provides image smoothing and segmentation suitable for the
20 extraction of perceived colors.

21 Figure 8 is a logic flow diagram that illustrates an example of a method for constructing
22 the image representation that resembles the human observation of a scene and its color
23 content. This method is designed to simulate the processes conducted in the early stages
24 of the human visual system, which performs significant amount of spatial averaging. At
25 step 801, the input image is subjected to a chromatic adaptation transform, to eliminate
26 the differences caused by different illumination conditions. Step 802 performs edge
27 detection. Using the edge information, step 803 performs pixel labeling to distinguish

1 between different types of pixels (e.g. uniform pixels, texture, region boundaries, noise,
2 etc.). In step 804 the image is adaptively smoothed, where the amount of smoothing is
3 determined based on pixel labels. In step 805, the image is subjected to image
4 segmentation to detect important regions and objects in the image. All the steps are
5 conducted by the data processor 101 under the control of a program or program stored in
6 the memory 103.

7 More specifically, the first step (801) in the described method uses an application of a
8 chromatic adaptation transform, that will compensate for the differences in illumination
9 conditions, with respect to both intensity and spectral characteristics. The present
10 embodiment, utilizes the Von Kries algorithm known to those skilled in the art, to
11 accomplish this task. However it should be noted that experiments have demonstrated
12 that any procedure that stretches the gray axis of the original image and realigns it with
13 the theoretical gray axis for perfectly homogeneous flat-spectrum illumination, performs
14 well in the given problem.

15 The following steps (802-805) in the method perform spatial averaging and image
16 segmentation that simulate the way humans perceive the color content of images. More
17 specifically, in its early stages the human visual system performs significant amount of
18 spatial averaging, which accounts for the way humans interpret color information. The
19 smoothing process is partly due to the nature of the channel between the retina and the
20 visual cortex, where the neighboring receptors converge into one ganglion, while the
21 groups of ganglions converge to single neurons in the visual cortex. However, the
22 amount of averaging depends on the spatial frequencies, spatial relationships among
23 colors, size of the observed objects and the global context. For example, it is well known
24 that the capability of the human visual system to distinguish different colors drops rapidly
25 for high spatial frequencies. Consequently, humans describe textured areas with a single
26 color, since only spatial averages of the microvariations are perceived. On the other hand,
27 the human visual system does not average isolated edges, as they represent object and
28 region boundaries. Based on these observations, the smoothing and segmentation are

1 carried out by modeling human perception as an adaptive low-pass filter operation, i.e.
2 convolution of the input image with a localized kernel.

3 Figure 9 shows a logic flow diagram that illustrates an example of an implementation of
4 the image smoothing algorithm, followed by the detection of important regions and
5 objects in the image. The method is assumed to be executed by the data processor 101
6 under control of a program or program stored in the memory 103. In step 901, the input
7 image is processed according to the Von Kries transform to eliminate differences in the
8 illumination conditions. Step 902, computes the amount of local contrast for each pixel in
9 the image. In step 903 these values are used to determine if picture represents an edge.
10 Step 904 computes the mean and variance of edge density in a neighborhood of each
11 image pixel. In step 905, the means and variances are used to label pixels into different
12 pixel types (e.g. noise, uniform, color edge, texture edge, coarse texture, fine texture). In
13 step 906, pixel labels are used to control the amount of Gaussian smoothing. In step 907,
14 the smoothed image is subjected to color segmentation.

15 With even more details, an embodiment of this method, may start by reducing the number
16 of colors in the image via use of, for example, the LBG vector quantization algorithm.
17 The result of color quantization represents a set of colors that optimally represent image
18 colors in the Lab space. The next step is to compute the local color contrast, $con(x,y)$, for
19 each image pixel (x,y) and use it to determine if the pixel represent an edge (e.g. the
20 pixel is considered an edge if its contrast exceeds a predefined threshold con_{min}). In the
21 next step, to distinguish between the uniform regions, texture areas, and contour points, a
22 sliding window is used to estimate the mean m , and variance v , of edge density for each
23 pixel. Depending on these estimates the pixels are labeled as: TYPE 1) uniform, $m = 0$,
24 TYPE 2) noise, $m < t_{m1}$, TYPE 3) color edge, i.e. edge between two uniform regions,
25 $t_{m1} < m < t_{m2}$, TYPE 4) texture edge, i.e. transition between uniform and textured region (or
26 between two textured regions), $t_{m2} < m < t_{m3}$, TYPE 5) coarse texture, $m > t_{m3}$, $v > t_v$, or TYPE
27 6) fine texture, $m > t_{m3}$, $v < t_v$. The labeling operation produces pixel maps, which control

1 the smoothing process and determine the computation of dominant colors in the
2 following way. The pixels labeled as noise are first removed, i.e. their color is changed
3 into the surrounding uniform color. Since the human eye creates a perception of a single
4 dominant color within uniform regions, the amount of smoothing is largest for the
5 uniform pixels. To allow for the highest amount of smoothing, the radius of the
6 smoothing kernel is chosen adaptively for each uniform pixel, depending on the distance
7 to the closest edge (color or texture). Pixels labeled as color edge (TYPE 3) and texture
8 edge (TYPE 4) are not filtered. Also, since edges do not contribute to the way humans
9 describe color content, these pixels are not used in the computation of color composition.
10 Finally, the amount of averaging performed in textured areas is chosen based on the edge
11 density, so that the amount of averaging is higher for fine textures and lower for coarse
12 textures. Thus, the perceived color at the location (x, y) , $pc(x, y)$, is computed as:

13 $pc(x, y) = (c * g_{N(x, y)})(x, y)$, where $g_{N(x_c, y_c)}(x, y)$ is the Gaussian kernel defined as:

14

$$g_{N(x_c, y_c)}(x, y) = k \exp\left(-\frac{x^2 + y^2}{\sigma^2}\right), \quad \sum_{x^2 + y^2 < N(x_c, y_c)} g_{N(x_c, y_c)}(x, y) = 1$$

15 and $N(x, y)$ is the radius of the kernel, which depends on the type of pixel in the center of
16 the kernel, (x_c, y_c) , as:

17

$$N(x, y) = \begin{cases} \|(x, y) - (x_e, y_e)\|, & \text{uniform region, i.e. } (x_c, y_c) \text{ is Type 1} \\ D, & \text{coarse texture, i.e. } (x_c, y_c) \text{ is Type 5} \\ 2D, & \text{fine texture, i.e. } (x_c, y_c) \text{ is Type 6} \end{cases}$$

18 and (x_e, y_e) is the edge pixel closest to (x, y) . As given by these formulas the smoothing
19 algorithm averages only within uniform and textured regions, thus simulating the
20 behavior of the human visual system. However, in reality, due to imperfections in
21 computing the edge maps, all the boundary pixels cannot be entirely excluded from the
22 smoothing operation. This produces some “graying out” of the resulting image, either
23 globally or in the specific regions. The desaturation of color may cause some regions to

1 be perceived and consequently named quite differently, and there may be a need to
2 consider some color-restoration scheme. Since the main goal is to preserve the same
3 appearance of colors to the human observer as the original image, the color-restoration
4 problem can be viewed as the color-constancy problem. Therefore, a chromatic
5 adaptation transform in the linear color space, may be applied again to stretch the gray
6 axis and minimize the color distortions introduced by averaging across different regions.

7 In the next step, the smoothed and “color-restored” image is subjected to color
8 segmentation and used as an input to the color naming procedure. For image
9 segmentation, one uses a color-based segmentation algorithm known to those skilled in
10 the art.. Prior to the segmentation the color value for each pixel labeled as color edge or
11 texture edge is replaced with the color value of the closest uniform or texture region. The
12 resulting image is then used in conjunction with the color naming method to perform
13 different color naming tasks in images.

14 Figure 10 shows a logic flow diagram that illustrates an example of a method for
15 attaching a color name to the regions and objects in the image. The method is assumed to
16 be executed by the data processor 101 under control of a program or program stored in
17 the memory 103. At step 1001, the input image is subjected to image smoothing and
18 segmentation. At step 1002 the data processing system computes perceived color for each
19 region and each object identified by the step 1001. At step 1003, the data processing
20 system 101 uses the color naming metric to compute the color name for each image
21 region, using its perceived color value as the input into the color naming algorithm, In
22 this embodiment, the perceived color value of the image region is computed by averaging
23 the color values of all perceptually important pixels from that region. Pixel color values
24 are advantageously specified in a linear color space. In current, but not limited
25 implementation of the method, all pixels labeled uniform, coarse texture and fine texture
26 are considered perceptually important, while pixels labeled noise, color edge, and texture
27 edge are not used in computation.

1 Figure 11 shows an example of the result of image smoothing, region detection, and
2 attaching the color names to the important regions and objects in the image. Figure 11
3 shows: (A) an original input image , (B) image after the chromatic adaptation transform,
4 (C) pixel map with pixels identified as uniform (white pixels), (D) pixel map with color
5 and texture edges (white pixels), (E) pixel map with pixels identified as texture (white
6 pixels), (F) image obtained as a result of adaptive smoothing, (G) image obtained as a
7 result of color segmentation, and (H) image with color names attaches to all important
8 regions.

9 Figure 12a shows a logic flow diagram that illustrates an example of a method for
10 pointing out examples of selected color in the image. The method is assumed to be
11 executed by the data processor 101 under control of a program or program stored in the
12 memory 103. At step 1201, the input image is subjected to image smoothing and
13 segmentation. At step 1202 the data processing system computes the perceived color for
14 each region and each object identified by the step 1201. At step 1203, the data processing
15 system 101 uses the color naming metric to compute the color name for each image
16 region, based on its perceived color value. At step 1204, using the GUI 104 and 105, the
17 user specifies and example color (or colors) ca. At step E, the data processor 101 searches
18 all the color names in the input image to find all the occurrences of color name ca. At step
19 1205, using the display part of the GUI 104, the data processing system displays to the
20 user the search result for the given image.

21 Figure 12b shows a logic flow diagram that illustrates a method for replacing a selected
22 color with a different color. The method is assumed to be executed by the data processor
23 101 under control of a program or program stored in the memory 103. At step 1210, the
24 input image is subjected to image smoothing and segmentation. At step 1211 the data
25 processor 101 computes the perceived color for each region and each object identified by
26 the step 1210. At step 1212, the data processor 101 uses the color naming metric to
27 compute the color name for each image region, based on its perceived color value. At step
28 1213, using the GUI 104 and 105, the user specifies the color (or colors) to be replaced

1 ca, and the replacement color (or colors) cb. At step 1214, the data processor 101
2 searches all the color names in the input image to find all the occurrences of color name
3 ca. At step 1215, the data processor 101 replaces all the pixels having color ca, with the
4 pixels having color cb.

5 An important application of these teachings is for example, in a method for automatically
6 generating a verbal description of overall color composition in images. If the color name
7 vocabulary and syntax are derived in a perceptual way, to reflect human behavior in color
8 categorization, the teachings of this invention allow for describing color composition at
9 different accuracy levels. These different precision levels correspond to different color
10 naming patterns in humans. For example, people mostly use fundamental level when
11 referring to well-known objects, or when color-related information is not considered
12 important. According to the described subjective experiments, the descriptions of
13 photographic images are mainly formulated with the coarse or medium precision, while
14 the color names at the detailed level are typically used when describing specific objects or
15 regions, or emphasizing the difference among them. Specifically: 1) fundamental level
16 captures the behavior of our subjects in the Color Listing Experiment, 2) descriptions of
17 the photographic images in the Color Composition Experiment were mainly given with
18 the coarse or medium precision, and 3) color names at the detailed level were used when
19 describing isolated color samples (Color Naming Experiments), or specific objects and
20 regions (Color Composition Experiment).

21 Figure 13 illustrates one example, but not limited embodiment of the rules that describe
22 different accuracy levels in expressing the color composition of an image. These rules are
23 derived based in the findings from the previously described subjective experiments. More
24 specifically, at the fundamental level, the color names are expressed as <generic hue> or
25 <generic achromatic term> from the syntax described in Figure 2. At the coarse level,
26 color names are expressed as <luminance> <generic hue>, or <luminance> <generic
27 achromatic term>. At the medium level, color names are obtained by adding the

1 <saturation> to the coarse descriptions. Finally, at the detailed level, the complete <color
2 name> as specified in Figure 2 is used.

3 Figure 14 shows a logic flow diagram that illustrates an example of a method for the
4 computation of the verbal description of the color composition of an input image. The
5 method is generally executed by the data processor 101 eliminates all the perceptually
6 insignificant colors, or remaps them into the closest perceptually important color. In
7 current but not limited embodiment of this method, noise pixels, which are not perceived
8 by the human visual system, are remaped into the closest uniform color, while the other
9 perceptually insignificant pixels (such as region boundaries, and transitions between the
10 regions) are eliminates (i.e. these pixels are not considered in the next steps). At step
11 1403, the data processor 101 computes the color name for each perceptually significant
12 image pixel, based on its color value. At step 1404, the data processing system loads a set
13 of rules that describe different color naming patterns in humans. At step 1405, the data
14 processor 101 computes the histogram of color names for each accuracy level. Figure 15
15 shows an example of results of the computation of color composition.

16 It should be noted that while the foregoing methods and system can be used to attach
17 color names to individual pixels, samples of color, regions and objects in images and to
18 derive the description of color composition, they can be used in many other applications
19 involving manipulation with color values, color analysis and color naming in image
20 processing, video processing, visualization, computer graphics and human-machine
21 interaction. To start with, using color names to label regions can often improve the result
22 of image segmentation, since the neighboring regions that share the same color name can
23 be merged. In many cases color names only, or in combination with other features (such
24 as spatial attributes, boundary and size features), can provide valuable information about
25 the analyzed images and reveal their semantics. For example, as illustrated in Fig 16a,
26 regions labeled vivid blue or vivid purplish blue found in the upper part of the image,
27 may represent sky on a bright sunny day. In the same picture regions with regular
28 boundaries/geometry and bright saturated colors are very likely to be man-made objects.

1 Similarly, the flowers shown in Figure 16b can be easily detected based on the
2 relationships between the curvature and color of the vivid reddish purple region, and the
3 neighboring green regions. Overall color composition, as generated with the teachings of
4 this invention, often captures the atmosphere in the scene. For example, by combining the
5 linguistic terms from the color name syntax described in teachings of this invention, the
6 scene shown in Figure 15b can be described as “brownish”, and easily related to a
7 man-made environment. Another example of what can be accomplished by adding the
8 color naming ability to the traditional image features (e.g. regions, lines, texture, etc.). By
9 merging all the descriptors, as shown in Figure 16c, it can be easily concluded that the
10 image is very likely to be an outdoor scene, probably a cityscape or a man-made structure
11 seen from the large viewing distance. Assuming the hypothesis is correct, a step further
12 would be to conclude “the weather wasn’t really nice when the picture was taken”. Color
13 naming ability may be implemented as a part of Artificial Intelligence Systems. For
14 example it is also within a scope of these teachings to manipulate a robot by naming and
15 describing the objects it should pick from the production line. In such a case a digital
16 image robot receives would be subjected to the processing shown in Figure 10, and the
17 spatial location of the named color within the digital image, would be remapped to the
18 actual physical location on the production line.

19 Thus the present invention provides a method employing a vocabulary of color names in
20 assigning a color name to a pixel in a digital representation, including the steps of:
21 providing the vocabulary of color names with a plurality of color prototypes, each color
22 prototype having a prototype color name and a corresponding prototype color value;
23 comparing a pixel color value of the pixel to the prototype color value of each color
24 prototype in the vocabulary, and obtaining a color match value for said each color
25 prototype in the vocabulary; determining a closest color match value resulting from the
26 step of comparing; and assigning to the pixel a particular prototype color name
27 corresponding to the closest match value.

1 In some embodiments the method includes forming the vocabulary of color names,
2 includes the steps of: obtaining at least one general set of essential color names, each
3 essential color name having a corresponding color value; whereby each color name
4 includes a hue descriptor, brightness modifier, and saturation modifier; and selecting a
5 subset of at least one general set in meeting an application desire for the vocabulary of
6 color names; and/or acquiring a digital representation of a scene, employing the
7 vocabulary in providing a description of a color composition in the scene.

8 Thus the present invention provides a method obtaining a vocabulary of color names,
9 acquiring a digital representation of a scene, and employing the vocabulary in providing a
10 description of a color composition in the scene.

11 The aspects of this invention also provides a tool for enriching user interfaces and
12 man-machine interaction. For example, a techniques made possible by this invention,
13 may allow a web designer to select and manipulate colors for the web page via a voice
14 interface and speech recognition system. The same tools apply to many design processes,
15 such as interior design, coloring of CAD models, architecture, design of textiles and
16 prints, etc. The methods may be included as a part of e-commerce tools, where a user may
17 type his search for a “light brown sofa”, and in addition to the text search, a database of
18 images may be analyzed to find the objects that match the description.

19 Therefore, while methods and system have been disclosed for deriving color names of
20 individual colors, color samples image pixels, and for describing colors and color
21 composition in images, it should be appreciated that these teachings are not to be limited
22 to only the presently described embodiments disclosed herein, nor is this invention to be
23 limited in any way by the specific examples of color names, color syntax, color naming
24 rules and subject matter that were disclosed above.

25 Thus it should be apparent that these teachings are clearly not intended to be limited only
26 to processing color values and collection of digital images stored in a computer memory

1 devices, or in some form of computer readable media. As such, the various descriptions
2 found above should be viewed as being exemplary of the teachings of this invention, as
3 these descriptions were provided as an aid in understanding the teachings of this
4 invention, and were not intended to be read in a limiting sense upon the scope and
5 practice of this invention.

6 In some embodiments, the invention is an article of manufacture comprising a computer
7 usable medium having computer readable program code means embodied therein for
8 causing assignment of a color name, the computer readable program code means in said
9 article of manufacture comprising computer readable program code means for causing a
10 computer to effect the steps of a method of this invention. In other embodiments, the
11 invention is implemented as a program storage device readable by machine, tangibly
12 embodying a program of instructions executable by the machine to perform method steps
13 for assigning a color name, said method steps comprising the steps of a method of this
14 invention.

15 The present invention can be realized in hardware, software, or a combination of
16 hardware and software. A visualization tool according to the present invention can be
17 realized in a centralized fashion in one computer system, or in a distributed fashion where
18 different elements are spread across several interconnected computer systems. Any kind
19 of computer system - or other apparatus adapted for carrying out the methods and/or
20 functions described herein - is suitable. A typical combination of hardware and software
21 could be a general purpose computer system with a computer program that, when being
22 loaded and executed, controls the computer system such that it carries out the methods
23 described herein. The present invention can also be embedded in a computer program
24 product, which comprises all the features enabling the implementation of the methods
25 described herein, and which - when loaded in a computer system - is able to carry out
26 these methods.

1 Computer program means or computer program in the present context include any
2 expression, in any language, code or notation, of a set of instructions intended to cause a
3 system having an information processing capability to perform a particular function
4 either directly or after conversion to another language, code or notation, and/or
5 reproduction in a different material form.

6 Thus the invention includes an article of manufacture which comprises a computer usable
7 medium having computer readable program code means embodied therein for causing a
8 function described above. The computer readable program code means in the article of
9 manufacture comprises computer readable program code means for causing a computer to
10 effect the steps of a method of this invention. Similarly, the present invention may be
11 implemented as a computer program product comprising a computer usable medium
12 having computer readable program code means embodied therein for causing a function
13 described above. The computer readable program code means in the computer program
14 product comprising computer readable program code means for causing a computer to
15 effect one or more functions of this invention. Furthermore, the present invention may be
16 implemented as a program storage device readable by machine, tangibly embodying a
17 program of instructions executable by the machine to perform method steps for causing
18 one or more functions of this invention.

19 It is noted that the foregoing has outlined some of the more pertinent objects and
20 embodiments of the present invention. This invention may be used for many
21 applications. Thus, although the description is made for particular arrangements and
22 methods, the intent and concept of the invention is suitable and applicable to other
23 arrangements and applications. It will be clear to those skilled in the art that
24 modifications to the disclosed embodiments can be effected without departing from the
25 spirit and scope of the invention. The described embodiments ought to be construed to
26 be merely illustrative of some of the more prominent features and applications of the
27 invention. Other beneficial results can be realized by applying the disclosed invention in

1 a different manner or modifying the invention in ways known to those familiar with the
2 art.